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Therefore  $\cos(-\theta) = \cos \theta$  and  $\sec(-\theta) = \sec \theta$  ;  $\sin(-\theta) = -\sin \theta$  ;  $\tan(-\theta) = -\tan \theta$  ;  $\cot(-\theta) = -\cot \theta$  ;  $\operatorname{cosec}(-\theta) = -\operatorname{cosec} \theta$ . Compound Angles: If an angle is expressed as the algebraic sum or difference of two or more angles, then it is called compound angle. 72 Engineering Mathematics-I.

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$y' + xy^2 - 4x^3 = 0$  ( $y'$ )<sup>3/2</sup> +  $x^2 - \cos(xy')$  = 0. A solution of a first-order ODE is a function which satisfies the equation. For example,  $y(x) = e^{2x}$  is a solution of  $y' -$

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$2y = 0$ .  $y(x) = x^2$  is a solution of  $xy' = 2y$ . A solution which appears as an implicit function, given in the form.

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$r_1 : \sin \cos. \frac{d}{dr} r \theta = \theta$ . ie.,  $(\theta) + \theta \theta \theta \phi = \cos 1 \tan \cos 1 - \tan \cot 1 : \cot 2$   
 $\cot \phi^2 = \theta$ . ie.,  $\cot 1 \cot (\phi) \phi = \pi/4 + \theta$ .  $\therefore \phi_1 - \phi_2 = \pi/4 + \theta - \theta = \pi/4$  The angle of intersection is  $\pi/4$ . Engineering Mathematics - I Dr. V. Loksha. 10 MAT11.

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1 Change in velocity  $v = v_2 - v_1$  The symbol means a small but finite change in something such as T, t, , x, v and so on. Consider the following. The distance moved by an object is directly proportional to time t as shown on the graph. Figure 1 Velocity = Change in distance/change in time.  $v = x/t$

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