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Offers unified treatment of conventional and modern continuous and discrete control theory and demonstrates how to apply the theory to realistic control system design problems. Along with linear and nonlinear, digital and optimal control systems, it presents four case studies of actual designs. The majority of solutions contained in the book and the problems at the ends of the chapters were generated using the commercial software package, MATLAB, and is available free to the users of the book by returning a postcard contained with the book to the MathWorks, Inc. This software also contains the following features/utilities created to enhance MATLAB and several of the MathWorks' toolboxes: Tutorial File which contains the essentials necessary to understand the MATLAB interface (other books require additional books for full comprehension), Demonstration m-file which gives the users a feel for the various utilities included, OnLine HELP, Synopsis File which reviews and highlights the features of each chapter.

During the 90s robust control theory has seen major advances and achieved a new maturity, centered around the notion of convexity. The goal of this book is to give a graduate-level course on this theory that emphasizes these new developments, but at the same time conveys the main principles and ubiquitous tools at the heart of the subject. Its pedagogical objectives are to introduce a coherent and unified framework for studying the theory, to provide students with the control-theoretic background required to read and contribute to the research literature, and to present the main ideas and demonstrations of the major results. The book will be of value to mathematical researchers and computer scientists, graduate students planning to do research in the area, and engineering practitioners requiring advanced control techniques.

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